6.641 Electromagnetic Fields, Forces, and Motion Spring 2009

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.

# 6.641, Electromagnetic Fields, Forces, and Motion Prof. Markus Zahn

# **Lecture 2: Differential Form of Maxwell's Equations**

### I. <u>Divergence Theorem</u>

# 1. Divergence Operation

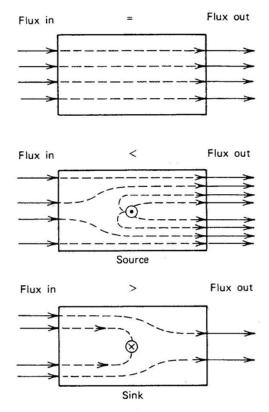


Figure 1-13 The net flux through a closed surface tells us whether there is a source or sink within an enclosed volume.

$$\oint_{S} \overline{A} \cdot \overline{dS} = \int_{V} div(\overline{A}) dV$$

$$\operatorname{div} \overline{A} = \lim_{\Delta V \to 0} \frac{\oint_{S} \overline{A} \cdot \overline{dS}}{\Delta V}$$

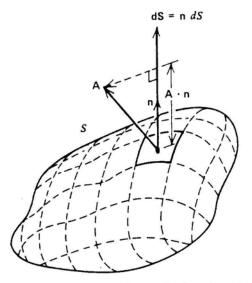


Figure 1-14 The flux of a vector  $\mathbf{A}$  through the closed surface S is given by the surface integral of the component of  $\mathbf{A}$  perpendicular to the surface S. The differential vector surface area element  $\mathbf{dS}$  is in the direction of the unit normal  $\mathbf{n}$ .

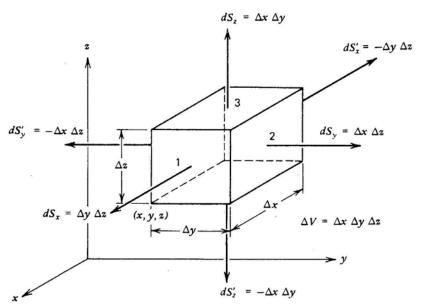


Figure 1-15 Infinitesimal rectangular volume used to define the divergence of a vector.

$$\begin{split} \Phi &= \int_{1}^{1} A_{x}\left(x,y,z\right) dydz - \int_{1'}^{1} A_{x}\left(x - \Delta x,y,z\right) dydz \\ &+ \int_{2}^{1} A_{y}\left(x,y + \Delta y,z\right) dxdz - \int_{2'}^{1} A_{y}\left(x,y,z\right) dxdz \\ &+ \int_{3}^{1} A_{z}\left(x,y,z + \Delta z\right) dxdy - \int_{3'}^{1} A_{z}\left(x,y,z\right) dxdy \\ \Phi &\approx \Delta X \Delta y \Delta z \left\{ \frac{\left[A_{x}\left(x,y,z\right) - A_{x}\left(x - \Delta x,y,z\right)\right]}{\Delta x} \right. + \left. \frac{\left[A_{y}\left(x,y + \Delta y,z\right) - A_{y}\left(x,y,z\right)\right]}{\Delta y} \right\} \\ &+ \left. \frac{\left[A_{z}\left(x,y,z + \Delta z\right) - A_{z}\left(x,y,z\right)\right]}{\Delta z} \right\} \\ &\approx \Delta V \left[ \frac{\partial A_{x}}{\partial x} + \frac{\partial A_{y}}{\partial y} + \frac{\partial A_{z}}{\partial z} \right] \\ &\text{div } \overline{A} = \lim_{\Delta V \to 0} \frac{\int_{3}^{1} \overline{A} \cdot d\overline{S}}{\Delta V} = \frac{\partial A_{x}}{\partial x} + \frac{\partial A_{y}}{\partial y} + \frac{\partial A_{z}}{\partial z} \\ &\text{Del Operator: } \overline{V} = \overline{i}_{x} \cdot \frac{\partial}{\partial x} + \overline{i}_{y} \cdot \frac{\partial}{\partial y} + \overline{i}_{z} \cdot \frac{\partial}{\partial z} \\ &= \text{div } \overline{A} \quad \overline{V} \cdot \overline{A} = \frac{\partial A_{x}}{\partial x} + \frac{\partial A_{y}}{\partial y} + \frac{\partial A_{z}}{\partial z} \end{split}$$

### 2. Gauss' Integral Theorem

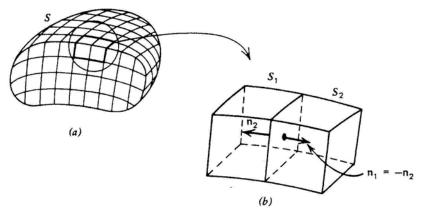


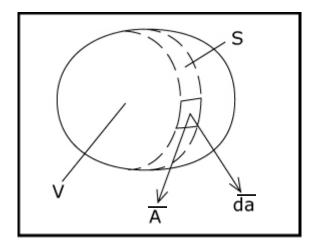
Figure 1-17 Nonzero contributions to the flux of a vector are only obtained across those surfaces that bound the outside of a volume. (a) Within the volume the flux leaving one incremental volume just enters the adjacent volume where (b) the outgoing normals to the common surface separating the volumes are in opposite directions.

$$\oint_{S} \overline{A} \cdot \overline{dS} = \sum_{\substack{i=1\\N \to \infty}}^{N} \oint_{dS_{i}} \overline{A} \cdot \overline{dS_{i}}$$

$$= \lim_{\substack{N \to \infty\\\Delta V_{n} \to 0}} \sum_{i=1}^{N} (\nabla \cdot \overline{A}) \Delta V_{i}$$

$$= \int_{V} \nabla \cdot \overline{A} dV$$

$$\int_{V} \nabla \cdot \overline{A} \, dV = \oint_{S} \overline{A} \cdot \overline{da}$$



# 3. Gauss' Law in Differential Form

$$\oint\limits_{S} \boldsymbol{\epsilon}_0 \ \overline{\boldsymbol{E}} \boldsymbol{\cdot} \overline{\boldsymbol{da}} = \int\limits_{V} \nabla \boldsymbol{\cdot} \left(\boldsymbol{\epsilon}_0 \overline{\boldsymbol{E}}\right) dV = \int\limits_{V} \boldsymbol{\rho} \, dV$$

$$\nabla \cdot \left( \epsilon_0 \overline{\mathsf{E}} \right) = \rho$$

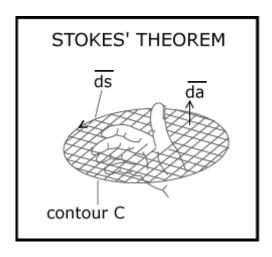
$$\begin{split} & \oint\limits_S \mu_0 \ \overline{H} \bullet \overline{da} = \int\limits_V \nabla \bullet \left( \mu_0 \overline{H} \right) dV = 0 \\ & \nabla \bullet \left( \mu_0 \overline{H} \right) = 0 \end{split}$$

### II. Stokes' Theorem

### 1. Curl Operation

$$\oint_{C} \overline{A} \cdot \overline{ds} = \int_{S} Curl(\overline{A}) \cdot \overline{da}$$

$$Curl\left(\overline{A}\right)_{n} = \lim_{da_{n} \to 0} \frac{\oint_{C} \overline{A} \cdot \overline{ds}}{da_{n}}$$



$$\int_{S} \nabla \times \overline{A} \cdot d\overline{a} = \oint_{C} \overline{A} \cdot d\overline{s}$$

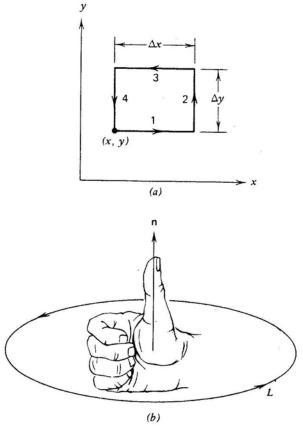


Figure 1-19 (a) Infinitesimal rectangular contour used to define the circulation. (b) The right-hand rule determines the positive direction perpendicular to a contour.

$$\oint_{C} \overline{A} \cdot \overline{ds} = \int_{\frac{x}{1}}^{x+\Delta x} A_{x}(x,y) dx + \int_{\frac{y}{2}}^{y+\Delta y} A_{y}(x+\Delta x,y) dy + \int_{\frac{x+\Delta x}{3}}^{x} A_{x}(x,y+\Delta y) dx 
+ \int_{\frac{y+\Delta y}{4}}^{y} A_{y}(x,y) dy 
= \Delta x \Delta y \left[ \frac{\left[ A_{x}(x,y) - A_{x}(x,y+\Delta y) \right]}{\Delta y} + \frac{\left[ A_{y}(x+\Delta x,y) - A_{y}(x,y) \right]}{\Delta x} \right] 
= da_{z} \left[ \frac{\partial A_{y}}{\partial x} - \frac{\partial A_{x}}{\partial y} \right] 
Curl  $(\overline{A})_{z} = \frac{\oint \overline{A} \cdot \overline{ds}}{da} = \frac{\partial A_{y}}{\partial x} - \frac{\partial A_{x}}{\partial y}$$$

By symmetry

$$\operatorname{Curl}\left(\overline{A}\right)_{y} = \frac{\oint \overline{A} \cdot \overline{ds}}{da_{y}} = \frac{\partial A_{x}}{\partial z} - \frac{\partial A_{z}}{\partial x}$$

$$\operatorname{Curl}\left(\overline{A}\right)_{x} = \frac{\oint \overline{A} \cdot \overline{ds}}{da_{x}} = \frac{\partial A_{z}}{\partial y} - \frac{\partial A_{y}}{\partial z}$$

$$Curl \overline{A} = \overline{i}_{x} \left[ \frac{\partial A_{z}}{\partial y} - \frac{\partial A_{y}}{\partial z} \right] + \overline{i}_{y} \left[ \frac{\partial A_{x}}{\partial z} - \frac{\partial A_{z}}{\partial x} \right] + \overline{i}_{z} \left[ \frac{\partial A_{y}}{\partial x} - \frac{\partial A_{x}}{\partial y} \right]$$

$$= \det \begin{bmatrix} \vec{i}_x & \vec{i}_y & \vec{i}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{bmatrix}$$

$$=\nabla \times \overline{A}$$

### 2. Stokes' Integral Theorem

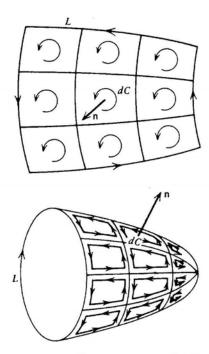


Figure 1-23 Many incremental line contours distributed over any surface, have nonzero contribution to the circulation only along those parts of the surface on the boundary contour L.

$$\lim_{N \to \infty} \sum_{i=1}^{N} \oint_{dC_{i}} \overline{A} \cdot \overline{ds}_{i} = \oint_{C} \overline{A} \cdot \overline{ds}$$

$$= \sum_{i=1}^{N \to \infty} (\nabla \times \overline{A}) \cdot \overline{da}_{i}$$

$$= \int_{S} (\nabla \times \overline{A}) \cdot \overline{da}$$

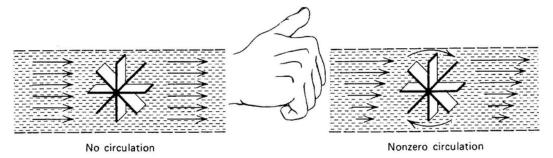


Figure 1-20 A fluid with a velocity field that has a curl tends to turn the paddle wheel. The curl component found is in the same direction as the thumb when the fingers of the right hand are curled in the direction of rotation.

3. Faraday's Law in Differential Form

$$\begin{split} & \oint\limits_C \overline{E} \bullet \overline{ds} = \int\limits_S \left( \nabla \times \overline{E} \right) \bullet \overline{da} = -\frac{d}{dt} \int\limits_S \mu_0 \ \overline{H} \bullet \overline{da} \\ & \nabla \times \overline{E} = -\mu_0 \ \frac{\partial \overline{H}}{\partial t} \end{split}$$

4. Ampère's Law in Differential Form

$$\oint_{C} \overline{H} \cdot \overline{ds} = \int_{S} \nabla \times \overline{H} \cdot \overline{da} = \int_{S} \overline{J} \cdot \overline{da} + \frac{d}{dt} \int_{S} \varepsilon_{0} \overline{E} \cdot \overline{da}$$

$$\nabla \times \overline{H} = \overline{J} + \varepsilon_{0} \frac{\partial \overline{E}}{\partial t}$$

# III. Applications to Maxwell's Equations

1. Vector Identity

$$\lim_{C \to 0} \oint_{C} \overline{A} \cdot \overline{ds} = 0 = \oint_{S} (\nabla \times \overline{A}) \cdot \overline{da} = \int_{V} \nabla \cdot (\nabla \times \overline{A}) dV$$
$$\nabla \cdot (\nabla \times \overline{A}) = 0$$

2. Charge Conservation

$$\nabla \cdot \left\{ \nabla \times \overline{H} = \overline{J} + \varepsilon_0 \frac{\partial \overline{E}}{\partial t} \right\}$$

$$0 = \nabla \cdot \left[ \overline{J} + \varepsilon_0 \frac{\partial \overline{E}}{\partial t} \right]$$

$$0 = \nabla \cdot \overline{J} + \frac{\partial \rho}{\partial t}$$

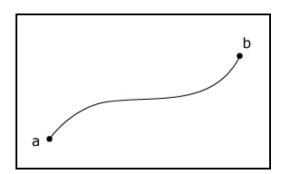
3. Magnetic Field

$$\nabla \cdot \left\{ \nabla \times \overline{E} = -\mu_0 \frac{\partial \overline{H}}{\partial t} \right\}$$

$$0 = -\frac{\partial}{\partial t} \left[ \nabla \cdot \mu_0 \overline{H} \right] \Rightarrow \nabla \cdot \left( \mu_0 \overline{H} \right) = 0$$

# 4. Vector Identity

$$\int\limits_{a}^{b}\overline{E}\bullet\overline{dI}=\Phi\left( a\right) -\Phi\left( b\right)$$

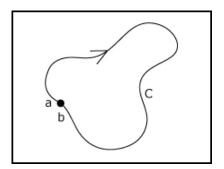


if a=b

$$\oint\limits_{C}\overline{E}\bullet\overline{dI}=\Phi\left(a\right)-\Phi\left(a\right)=0$$

$$\bar{\bar{\mathsf{E}}} = -\nabla \Phi$$

$$\oint\limits_{C}\nabla\Phi\bullet\overline{dI}=0$$



$$\int\limits_S \nabla \times \left(\nabla f\right) \bullet \overline{da} = \oint\limits_C \nabla f \bullet \overline{dI} = 0 \Rightarrow \nabla \times \left(\nabla f\right) = 0$$

## IV. Summary of Maxwell's Equations in Free Space

## **Integral Form**

# **Differential Form**

### Faraday's Law

$$\oint\limits_{C}\overline{E}\boldsymbol{\cdot}\overline{dI}=-\mu_{0}\,\frac{d}{dt}\int\limits_{S}\overline{H}\boldsymbol{\cdot}\overline{da}$$

$$\nabla \times \overline{E} = -\mu_0 \, \frac{\partial \overline{H}}{\partial t}$$

## Ampere's Law

$$\oint\limits_C \overline{H} \boldsymbol{\cdot} \overline{dI} = \int\limits_S \overline{J} \boldsymbol{\cdot} \overline{da} + \epsilon_0 \, \frac{d}{dt} \int\limits_S \overline{E} \boldsymbol{\cdot} \overline{da}$$

$$\nabla\times\overline{H}=\bar{J}+\epsilon_{_{0}}\,\frac{\partial\bar{E}}{\partial t}$$

### Gauss' Law

$$\oint_S \epsilon_0 \overline{E} \bullet \overline{da} = \int_V \rho dV$$

$$\nabla \bullet \left(\epsilon_0 \overline{\mathsf{E}}\right) = \rho$$

$$\oint\limits_S \mu_0 \; \overline{H} \bullet \overline{da} = 0$$

$$\nabla \cdot \left(\mu_0 \overline{H}\right) = 0$$

## Conservation of charge

1. 
$$\oint_C \overline{J} \cdot \overline{da} + \frac{d}{dt} \int_V \rho dV = 0$$

$$\nabla \bullet \bar{J} + \frac{\partial \rho}{\partial t} = 0$$

2. 
$$\oint_{S} \left[ \overline{J} + \varepsilon_0 \frac{\partial \overline{E}}{\partial t} \right] \cdot \overline{da} = 0$$

$$\nabla \bullet \left[ \overline{J} + \epsilon_0 \frac{\partial \overline{E}}{\partial t} \right] = 0$$

#### **EQS Limit**

$$\nabla \times \overline{\mathsf{E}} \approx \mathsf{0}, \ \overline{\mathsf{E}} = -\nabla \Phi$$

$$\nabla \times \overline{E} = -\mu_0 \, \frac{\partial \overline{H}}{\partial t}$$

$$\nabla \bullet \overline{\mathsf{E}} = -\nabla \bullet \left( \nabla \Phi \right) = -\nabla^2 \Phi = \frac{\rho}{\epsilon_0} \text{ (Poisson's Eq.)}$$

$$\nabla\times\overline{H}=\overline{J}$$

$$\Phi \left( {x,y,z} \right) = \iiint\limits_{x',y',z'} {\frac{{\rho \left( {x',y',z'} \right)dx'dy'dz'}}{{4\pi {\epsilon _0}\left[ {{\left( {x - x'} \right)^2} + {{\left( {y - y'} \right)^2} + {\left( {z - z'} \right)^2}} \right]^{\frac{1}{2}}}}}$$

$$\nabla \bullet \left(\mu_0 \overline{H}\right) = 0 \, \Longrightarrow \, \mu_0 \overline{H} = \nabla \times \overline{A}$$

$$\nabla^2 \overline{A} = -\mu_0 \overline{J}, \ \nabla \cdot \overline{A} = 0$$

$$\overline{A}\left(x,y,z\right) = \iiint\limits_{x',y',z'} \frac{\mu_{_{0}} \overline{J}\!\left(x',y',z'\right) dx' dy' dz'}{4\pi \! \left[\left(x-x'\right)^{\! 2} + \! \left(y-y'\right)^{\! 2} + \! \left(z-z'\right)^{\! 2}\right]^{\! \frac{1}{2}}}$$